INVESTIGATION OF MECHANICAL LOADING OF PV MODULES BY CLEANING ROBOT 2

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Aim of investigation

→ Evaluation and quantification of mechanical loading of PV modules during drive with Solarcleano robot 2



Cleaning robot 2 from Solarcleano

Result of investigation

- With Solarcleano robot 2 several cleaning drives were done over PV modules (mounted according manufacturer specs / data sheet).
- Before and after electroluminescence images showed that the robot drives did not cause any cell cracks.
- The measured maximum deflection of the modules over all drives was 4.6 mm. This corresponds to a surface load on the entire module of about 300 Pa (compared to a wind load of 2,400 Pa; LAURA final report, funding code 0325716B).

Specimen

Following PV modules (SOLUXTEC Multi Series FR60 250Wp) were used for this investigation:

Sample number	Serial number	Initial STC power [W]
CSP_AMEMey_1_P06	D9220916375094	263,1
CSP_AMEMey_1_P07	D9220916375041	262,4

Module characterization

Power measurement

- Equipment: Berger class AAA Module flasher
- Parameter:
 - STC (standard test conditions): (25±1)°C, irradiation 1000 W/m², spectrum AM1.5
 - Measurement uncertainty ±2,5% without reference module
 - Repetitive accuracy <0,3% (95% confidence)
 - Note: modules were measured as delivered





Module characterization

Elektroluminescence

- Equipment:
 - Greateyes LumiSolarProfessional
 - Stripwise image acquisition and stitching to obtain a complete image of the complete solar module
- Parameters:
 - Current injection: 8,5 A
 - Exposure time: 5 s
 - Aperture: 2.8



Specifications		
resolution	up to 8 Mpx/32 Mpx	
Data depth	16bit = 65536 gray scales	
Substrate	mono-Si, poly-Si, a-Si, micro-Si, CIS, CIGS, CdTe Cells, Strings or Modules	
Size	max. 1.1 x 2.0 m	
Sensor	cooled Back-illuminated CCD	
	Model: GE 2048 512 BI MID	
	Pixel size: 13.5µm x 13,5µm	
	Max. Dynamic Range: 33333:1	
Exposure times	0.3 sec - 60 sec	



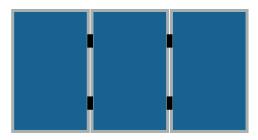
Setup & procedure

setup:

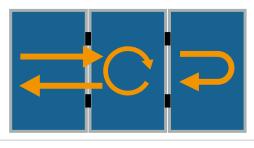
- Test setup with 3 horizontally placed/mounted PV modules
- Middle module as test module
- Edge modules as start and turn platform

procedure:

- Cleaning drive starting on start module (left)
- Passing over the test module
 - Straight line to illustrate the cleaning drive
 - Turning to illustrate cornering
- Turning on turning module



Test setup with 3 modules (left: start module, center: test module, right: turning module)

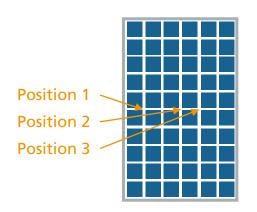


Procedure of test drive (scheme)

Evaluation

Evaluation:

- Elektroluminescence (EL) images of test module after test drive
- Comparison of EL images before and after test drive to evaluate mechanical loading
 - Possible cell cracks as quantification criteria
- Maximum deflection measurement at three positions

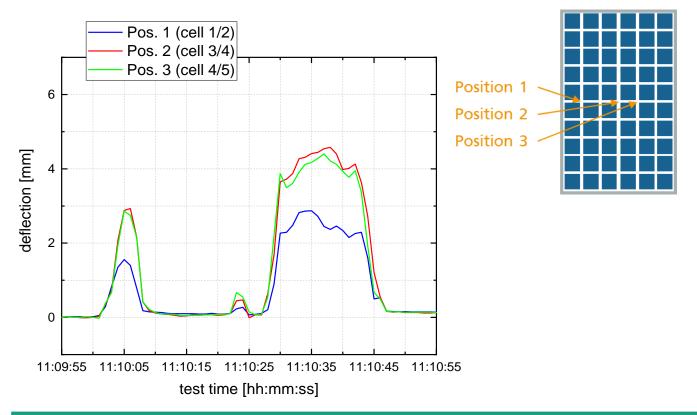


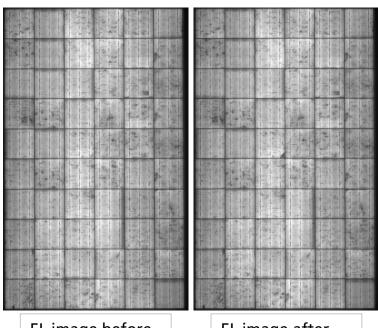
Positions of deflection measurement (left) and setup of mounting construction (without modules) displacement sensors (right)



Test drive 01

- Specimen: CSP_AMEMey_1_P06
- → No additional cell cracks, STC measurement omitted
- → Max. deflection = 4.6 mm





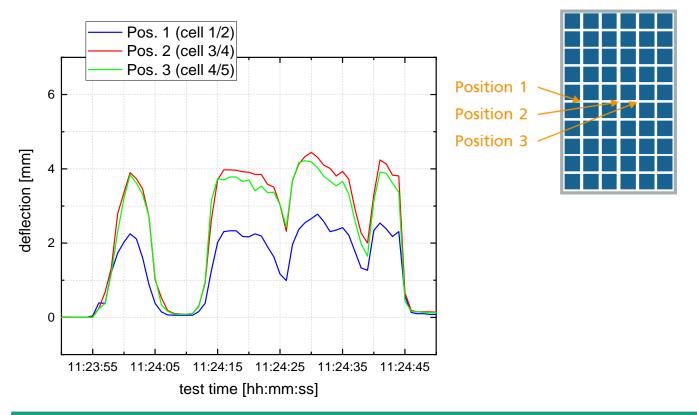
EL image before test drive

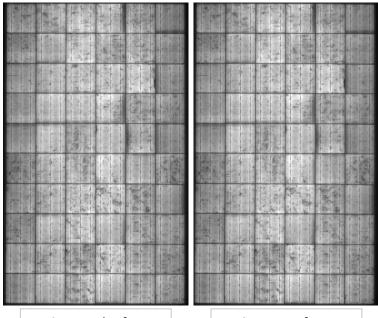
EL image after test drive



Test drive 02

- Specimen: CSP_AMEMey_1_P07
- → No additional cell cracks, STC measurement omitted
- Max. deflection = 4.4 mm





EL image before test drive

EL image after test drive

Evaluation of test drives

- Test drives 01 und 02 done over PV modules (mounted according manufacturer specs / data sheet).
- Both test drives without additional cell cracks
- maximum deflection of the modules over all drives of 4.6 mm
 (corresponds to a surface load on the entire module of about 300 Pa, compared to a wind load of 2,400 Pa; LAURA final report, funding code 0325716B)